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[C3] S Boche, X Zuo, S Schaefer and S Leutenegger,
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[C4] Y Ren, B Xu, CL. Choi and S Leutenegger,
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[C5] B Xu, A Davison and S Leutenegger,
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[J2] M Popovic, F Thomas, S Papatheodorou, N Funk, T Vidal-Calleja and S Leutenegger,
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[J3] N Funk, J Tarrio, S Papatheodorou, M Popovic, PF. Alcantarilla and S Leutenegger,
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[C2] D Tzoumanikas, Q Yan and S Leutenegger,
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[C3] U Bonde, PF Alcantarilla and S Leutenegger,
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[C4] Z Landgraf, F Falck, M Bloesch, S Leutenegger and AJ Davison,
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[C5] T Laidlow, J Czarnowski, A Nicastro, R Clark and S Leutenegger,
Towards the Probabilistic Fusion of Learned Priors into Standard Pipelines for 3D Reconstruction,
[C6] J Ortiz, M Pupilli, S Leutenegger and AJ Davison,
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[C7] D Tzoumanikas, F Graule, Q Yan, D Shah, M Popovic and S Leutenegger,
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[J2] K Zhang, P Chermprayong, D Tzoumanikas, W Li, M Grimm, M Smentoch, S Leutenegger and M Kovac,
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[J4] TK Kim, S Zafeiriou, B Glocker and S Leutenegger, 
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*Mid-fusion: Octree-based object-level multi-instance dynamic slam*, 

[C2] A Nicastro, R Clark and S Leutenegger, 
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*KO-Fusion: dense visual SLAM with tightly-coupled kinematic and odometric tracking*, 

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*Characterizing visual localization and mapping datasets*, 

[C7] M Bloesch, T Laidlow, R Clark, S Leutenegger and AJ Davison, 
*Learning meshes for dense visual SLAM*, 

[C8] E Vespa, N Funk, PH Kelly and S Leutenegger, 
*Adaptive-resolution octree-based volumetric SLAM*, 
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[J2] T Whelan, RF Salas-Moreno, B Glocker, AJ Davison and S Leutenegger,
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[C3] E Johns, S Leutenegger and AJ Davison,
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[C4] J Zienkiewicz, A Davison and S Leutenegger,
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